

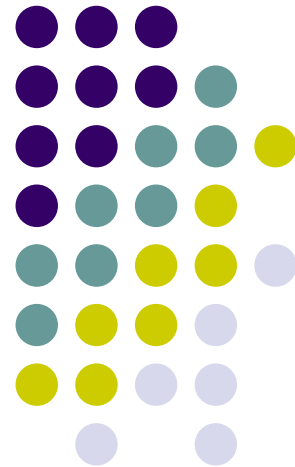
Enhancing Student Understanding of Formal Method through Prototyping



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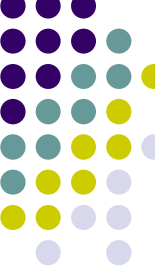
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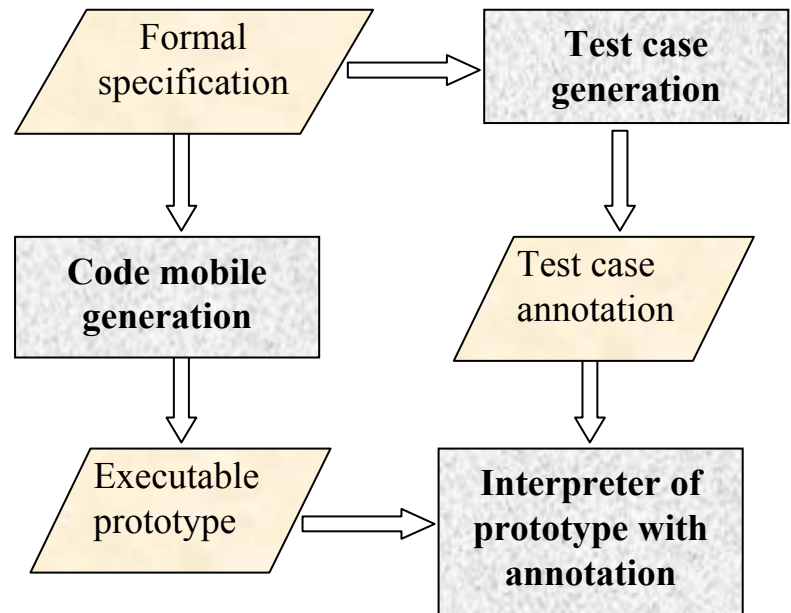
Plan

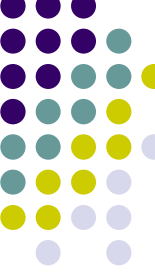
- Academic context
- Introduction
- Architecture of our teaching approach
 - Related work
 - Context and tool
- Direct application of formal method
- Case studies
 - Examples
 - SLP
- Conclusion



Academic Context

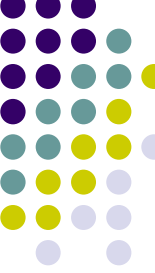
- **Subject** : formal methods for mobility
- **Objectives**:
 - To model mobile agent systems
 - To express properties about MA system
 - To generate and to enrich executable prototype
 - To have unit tests about it





Introduction

- **Message to students:**
 - Formal methods are necessary in achieving correct software
 - software that can be proven to fulfill its requirements.
 - Formal specifications are unambiguous and analyzable.
 - Building a formal model improves understanding.
 - The modeling of no determinism, communication, mobility, and other features in formal steps, allows design and implementation decisions to be made when most suitable.



Introduction

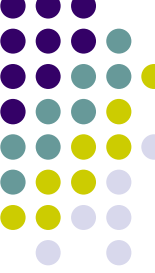
- **Answer from students**
 - Formal methods are not suitably supported with development tools,
 - They did not use or observe formal methods in their own industrial experience
 - Formal Methods are not widely used in software development.
 - Formal methods are based on mathematical manipulation and reasoning,
 - They are not confident and skilled in the use of mathematical techniques
 - The previous results of these courses are not well known,

Architecture of our teaching approach



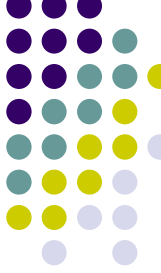
- **Mobility description:**
 - **Formal languages:** mobile Unity, HO-Pi Calculus, COOPN₂, Ambient calculus or join calculus, M-nets, etc
 - **Tools (Related work):**
 - mobility WorkBench (MWB for polyadic pi calculus),
 - COOPN plug-in (for Eclipse and NetBeans)
 - Bplug (Eclipse plug in for B specification)
 - Mython (Python tool for M-net specifier),
 - **Structure**
 - Tool = support of experience exchange
 - = ideal observer of student test

Architecture of our teaching approach



- 2002 **first version** of our plate form: HOPiTool
 - Formal language : Higher Order Pi Calculus
 - Key concepts :
 - Agent definition,
 - Higher order expression,
 - Exchange of terms between agents,
 - Operational semantics is clearly defined
 - Observations and equivalences are already defined,
 - Sorts and checking are also defined
 - Main constraints :
 - Open plate form for student extensions
 - Network tool for the managing of the agent hosts

Architecture of our teaching approach



● Context of the course

- Paris 12 university (computer science department), 35 hours
- Formal specification to master degree Computer Science students,
- 30 students
- 10 Lessons, 1 project per student, a weekly evaluation, 1 exam,

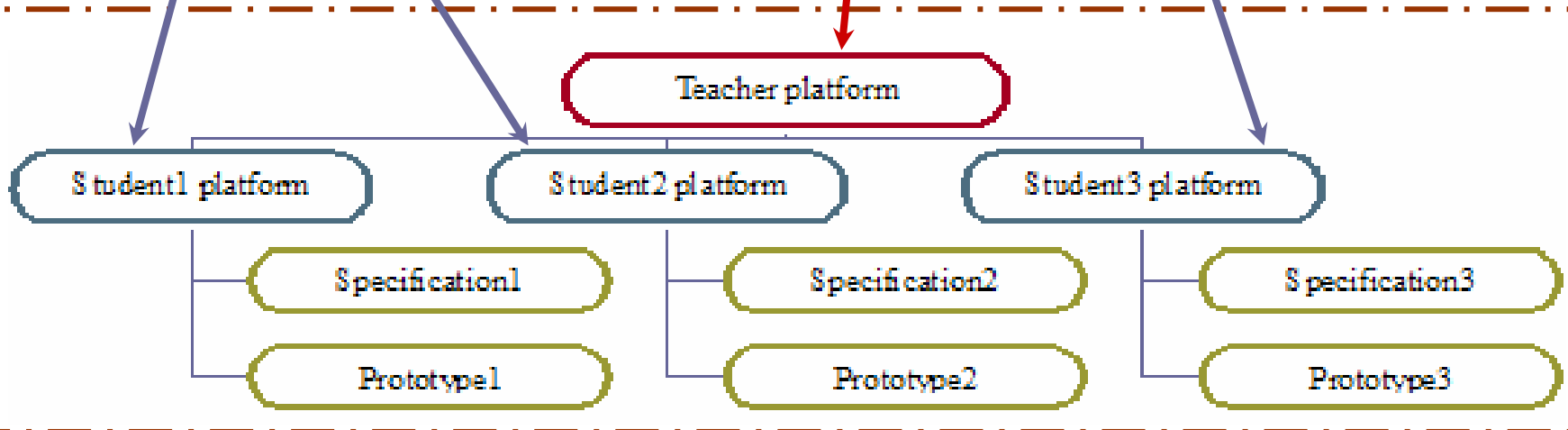
● Structure of the course

- an explanation of formal feature (i.e. deployment of an agent in a graph, etc.)
 - 1,5 hour
- direct application of previous subjects (i.e. the specification of a system based agents which control telnet protocol and forward information)
 - 1,5 hour – 2 hours
- subject of the evaluation

Direct application of formal method



- From specific requirements to specification
 - Student writes its own specifications
 - A student agent checks the results of each students through interactions with a teacher agent,
 - Report is generated for each contribution

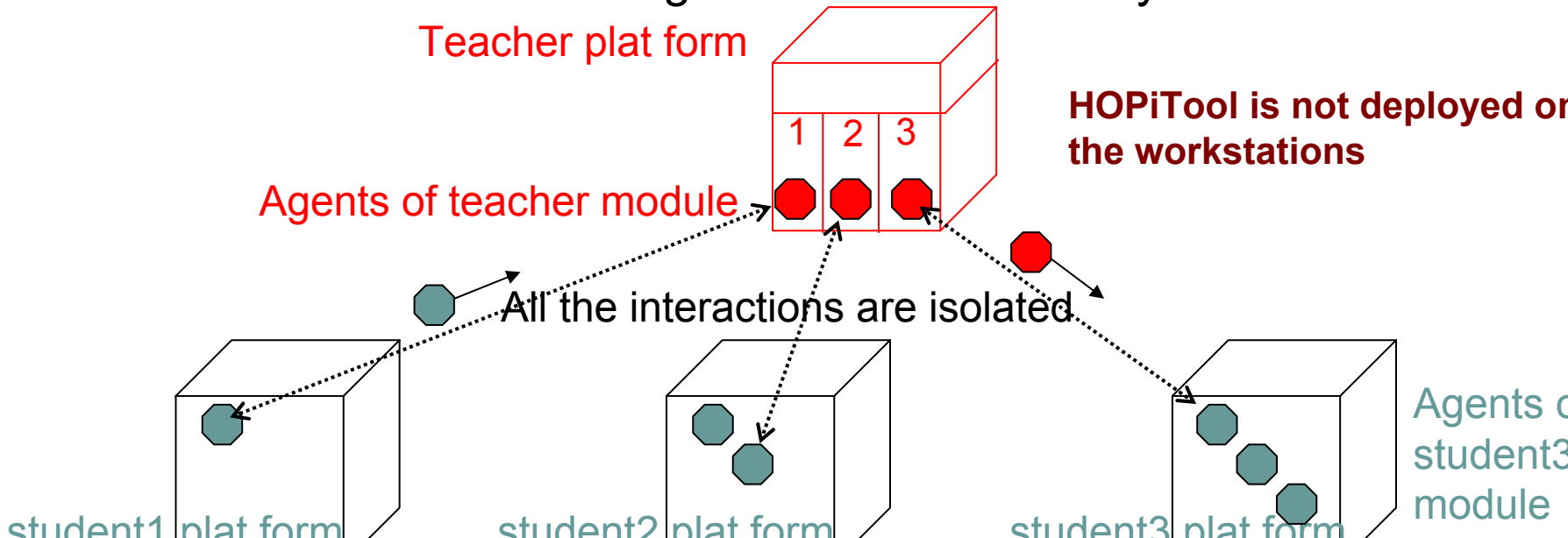


HOPiTool is deployed on all the workstations of this teaching network

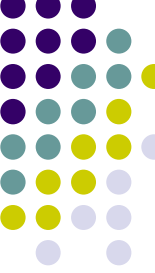
Direct application of formal method



- From specification to prototype (if previous step is OK)
 - Student generates code through HOPiTool and add some behavioral features (watch point, I / O, etc),
 - Compilation, deployment and configuration
 - Execution of the agents of the student system interaction with the agents of the teacher system.



Direct application of formal method

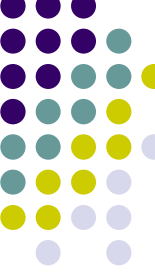


- Observations:

- For students
 - Interpretation of a scenario
 - Application of observations (Parrow, Sangiorgi)
 - Construction of inference tree for any agents
 - Report about the firing event

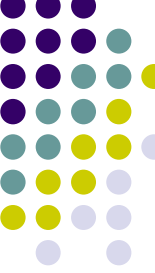
- Observations

- For teacher
 - Timing of the student work,
 - Bug tracking
 - Measure about all the results of a student group (statistics on difficulties, etc)
 - Definition of new metrics : equivalence relations, etc.



Case studies

- Student project examples
 - SLP protocol simulation
 - (Service Location Protocol)
 - Intrusion detection system
 - Login protocol is observed by agent which filters users
 - Mobile computing
 - Pi number calculus with BBP formula
 - Parallel bubble sort
 - Matrix computation
- Teacher deliverable
 - Requirements
 - A part of specification
 - The teacher agent
 - A register for the subscription of the students
 - All time events are saved
 - A teacher module of agents
 - Agents for the case study
 - Agents for student evaluation

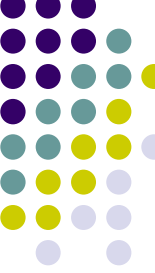


Case studies

- Service Location Protocol

- Subject: agent exportation and local activity
- Requirement: 5 agents are defined
 - 3 agents are specified by teacher (DA, DA_{Mem}, IdleDA_{Mem})
 - 2 agents have to be specified by student (SA, UA)
- First evaluation of specifications

- HOPiTool code generation
 - Java, Jini API
- Deployment over the network:
 - Lookup service are started
 - Teacher agent module is started
 - Student agent module is started
- Second evaluation of multi agent module



SLP Case study

- Scenario
 - Set of interactions between SA and DA
 - SA wants to publish a print service and a mail service (for the session) : first request
 - SA sends both services to DA and receives acknowledge
 - Set of interactions between UA and DA
 - UA looks for a print service : first request
 - UA receives a service from SA and uses it for printing a quiz

$DA(SrvRqst) = (\nu SrvRply) SrvRply(Service(print, msg), SrvRply).SrvRply(S(name, f)).UA(SrvRqst)$

$(SrvReg, SrvAck) = SrvReg(Service(print, msg).SrvAck.SA(SrvReg, SrvAck)$

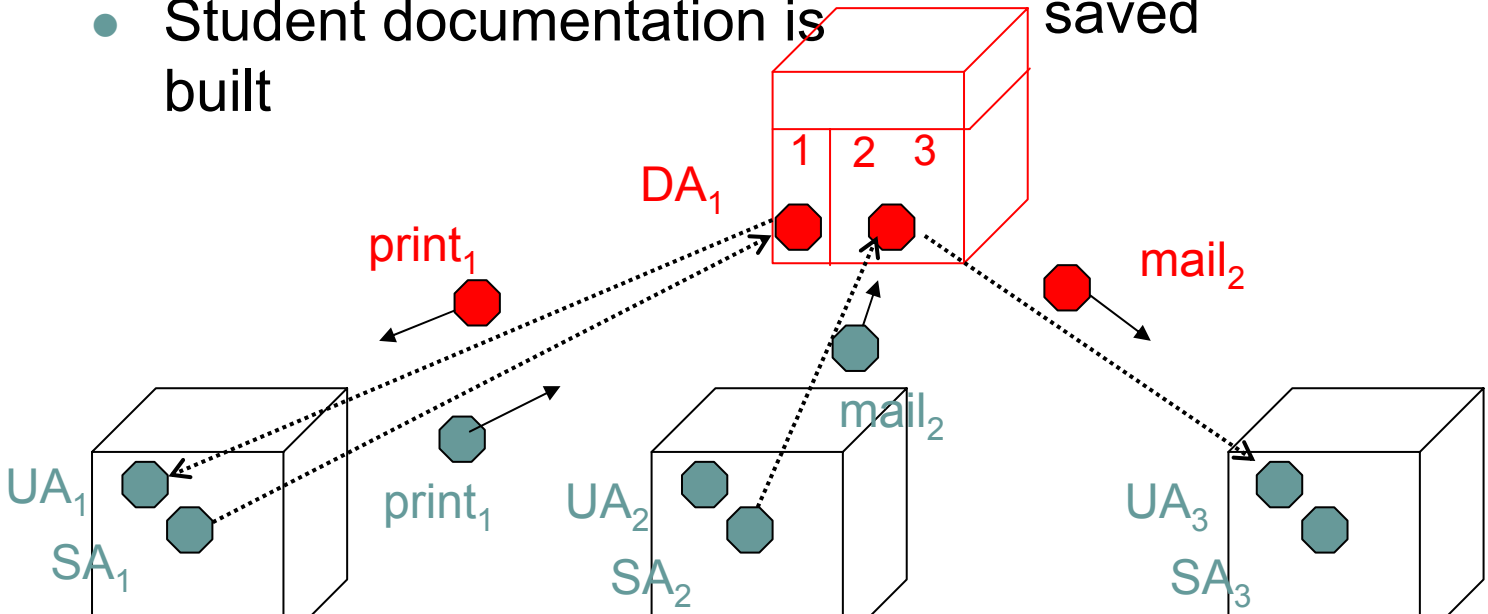
$DA(SrvReg, SrvRqst, SrvAck) = (SrvReg.(S(name, f).input(S(name, f).SrvAck)))$

$|((SrvRqst(S(name, f), SrvRply).name(SrvRply)).DA(SrvReg, SrvRqst, SrvAck))$



SLP Case study

- From specification
 - Mobile code is generated
 - Unit test cases are defined (JUnit and JDepend)
 - Student documentation is built
- From student mobile code
 - Services are published into global lookup service of HOPiTool
 - Results of test cases are saved

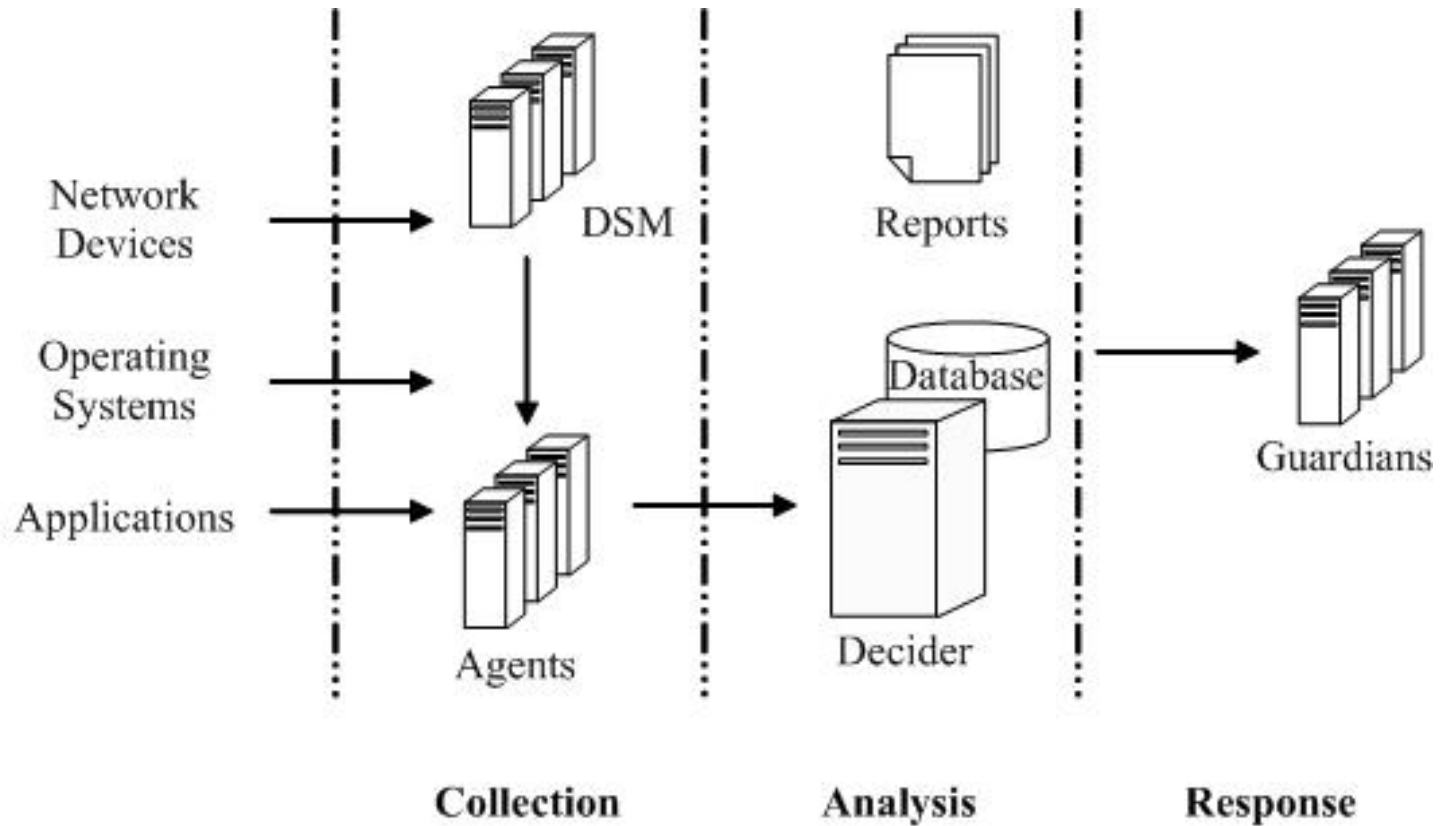


Conclusion

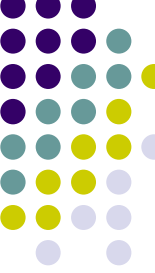


- Our teaching approach
 - Direct feedback : direct measure about student understanding
 - Same tool is used for direct application and final evaluation
 - Student projects bring new contribution to specification repository
 - Teacher contribution improves HOPiTool
 - new formal observations
 - New features like test cases or replay.
 - Tier-3 : 3 students work on Huntsman project
 - detection and denial of intruder attacks
 - www.tier-3.com

IDS – Architecture



BBP



Pi number formula

$$\pi = \sum_{i=0}^{\infty} \frac{1}{16^i} \left(\frac{4}{8i+1} - \frac{2}{8i+4} - \frac{1}{8i+5} + \frac{1}{8i+6} \right)$$

4 agents: one per contribution

A collector agent picks up each result and computes the value of the iteration.
An iterator agent computes the global approximation of all the collector